

Biophysics I

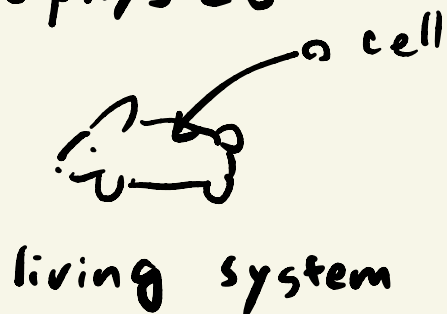
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2023

Spring

Biophysics I

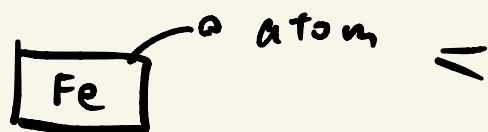
Lecture 1



interaction

Chemical reaction

Cf.) condensed matter



● Chemical reaction



dense.

Assumption

ideal dilute solution

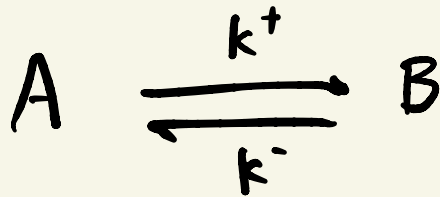
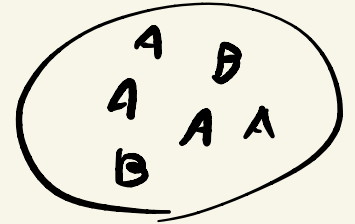
Not true,
but easy
and
practical

Example 1 : activity

A : active state

B : inactive state

cell



k^+, k^- ; rate constants

Assumption

macroscopic (• large number of molecules) Not true, but practical

C_A : concentration of A

C_B : concentration of B

$$C_A \geq 0, C_B \geq 0 \quad \left(\begin{array}{l} C_A \in \mathbb{R}_{\geq 0} \\ C_B \in \mathbb{R}_{\geq 0} \end{array} \right)$$

rate equation

$$\frac{dC_A}{dt} = -k^+ C_A + k^- C_B = -J(C_A, C_B)$$

$$\frac{dC_B}{dt} = k^+ C_A - k^- C_B = J(C_A, C_B)$$

$$\textcircled{1} \quad \frac{dC_A}{dt} = - \frac{dC_B}{dt}$$

$$\rightarrow \frac{d}{dt} (C_A + C_B) = 0$$

$$C_A + C_B = C = \text{const.}$$

more general

$$\alpha \in \mathbb{R}. \quad \frac{d}{dt} \alpha = 0$$

$$\frac{d}{dt} (\alpha C_A + \alpha C_B) = 0.$$

conservation law

②

$$C_A^{eq} > 0, \quad C_B^{eq} > 0, \quad \text{equilibrium}$$
$$J(C_A^{eq}, C_B^{eq}) = 0 \quad \left(\begin{array}{l} C_A^{eq} \in \mathbb{R}_{>0} \\ C_B^{eq} \in \mathbb{R}_{>0} \end{array} \right)$$

(Do not consider a trivial solution)
 $C_A = C_B = 0$

$$k^+ C_A^{eq} = k^- C_B^{eq}$$

$$\rightarrow \frac{C_A^{eq}}{C_B^{eq}} = \frac{k^-}{k^+}$$

law of mass action

(detailed balance)

$$C_A^{eq} + C_B^{eq} = C$$

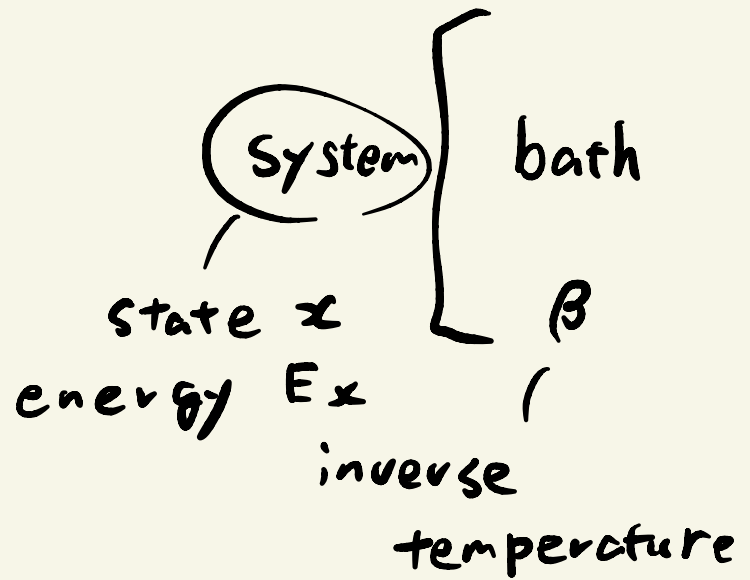
$$P_A = \frac{C_A^{eq}}{C} = \frac{1}{1 + \frac{C_B^{eq}}{C_A^{eq}}} = \frac{1}{1 + \frac{k^+}{k^-}}$$

$$P_B = \frac{C_B^{es}}{C} = 1 - P_A = \frac{\frac{k^+}{k^-}}{1 + \frac{k^+}{k^-}}$$

$$(P_A + P_B = 1, P_A \geq 0, P_B \geq 0)$$

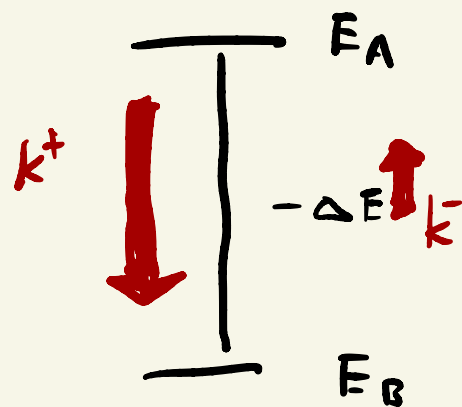
cf.) canonical distribution

$$P_x \propto \exp(-\beta E_x)$$



$$P_A = \frac{\exp(-\beta E_A)}{\exp(-\beta E_A) + \exp(-\beta E_B)}$$

$$= \frac{1}{1 + \exp(-\beta \underbrace{(E_B - E_A)}_{\Delta E})}$$



assumption



$$P_A = \frac{1}{1 + \frac{k^+}{k^-}}$$

physical interpretation

$$\frac{k^+}{k^-} = \exp(-\beta \Delta E)$$

$$\ln \frac{k^+}{k^-} = -\beta \Delta E$$

local
detailed
balance

③ matrix - vector notation

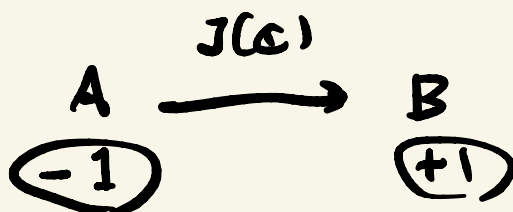
$$\mathbf{C} = \begin{pmatrix} C_A \\ C_B \end{pmatrix} \quad 2 \times 1 \text{ matrix}$$

$$J(\mathbf{C}) = J(C_A, C_B)$$

$$\frac{d}{dt} \mathbf{C} = \frac{d}{dt} \begin{pmatrix} C_A \\ C_B \end{pmatrix} = \begin{pmatrix} -J(\mathbf{C}) \\ J(\mathbf{C}) \end{pmatrix}$$

$$= \underbrace{\begin{pmatrix} -1 \\ 1 \end{pmatrix}}_{2 \times 1 \text{ matrix}} \underbrace{J(\mathbf{C})}_{1 \times 1 \text{ matrix}}$$

$$\mathbf{S} = \begin{pmatrix} -1 \\ +1 \end{pmatrix} \quad : \quad \text{Stoichiometric matrix}$$



● rank nullity theorem T: transpose

$A: n \times m$ (real valued) matrix

$$\text{rank}(A) = r \quad (\leq \min(n, m))$$

$$\left[\text{rank}(A) = \text{rank}(A^T) = \dim(\text{Im}(A)) = \dim(\text{Im}(A^T)) \right]$$

$$\ker(A) = \{x \in \mathbb{R}^m \mid Ax = 0\}$$

$$\ker(A^T) = \{x \in \mathbb{R}^n \mid A^T x = 0\}$$

$$\left[\begin{array}{l} \dim(\ker(A)) + r = m \\ \dim(\ker(A^T)) + r = n \end{array} \right]$$

$$\dim(\ker(A)) = m - r$$

$$\dim(\ker(A^T)) = n - r$$

$S: 2 \times 1$ matrix

$$\text{rank}(S) = 1$$

$$\dim(\ker(S)) = 1 - 1 = 0$$

$$\dim(\ker(S^T)) = 2 - 1 = \underline{1} \quad !$$

$$S^T = \begin{pmatrix} -1 & 1 \end{pmatrix}$$

$$S^T \begin{pmatrix} \alpha \\ \alpha' \end{pmatrix} = 0 \rightarrow \alpha' = \alpha.$$

$$\mathcal{Q} := \begin{pmatrix} \alpha \\ \alpha \end{pmatrix} = \alpha \begin{pmatrix} 1 \\ 1 \end{pmatrix} \in \ker(S^T)$$

$$\text{cf.)} \quad \frac{d}{dt} (\alpha c_A + \alpha c_B) = 0$$

$$\frac{d}{dt} (\mathcal{Q}^T \mathcal{C}) = 0 \quad \left(\begin{array}{l} \text{assumption} \\ \frac{d}{dt} \mathcal{Q} = 0 \end{array} \right)$$

Check

Rate equation

$$\frac{d}{dt} \mathcal{C} = S J(\mathcal{C})$$

$$\frac{d}{dt} (\mathcal{Q}^T \mathcal{C}) = \mathcal{Q}^T S J(\mathcal{C})$$

$$= [S^T \mathcal{Q}]^T J(\mathcal{C})$$

$$= 0^T J(\mathcal{C})$$

$$= 0$$

matrix A, B
 $(AB)^T = B^T A^T$
 $(A^T)^T = A$

Conservation law $\leftrightarrow \mathcal{Q} \in \ker(S^T)$
 $\mathcal{Q}^T \mathcal{C} = \text{const.}$

Summary



rate equation: $\frac{d}{dt} \mathbb{C} = S J(\mathbb{C})$

detailed balance $J(\mathbb{C}^{es}) = 0$
 $\mathbb{C}^{es} \in \mathbb{R}_{>0}^2$

local detailed balance

$$\ln \frac{k^+}{k^-} = -\beta \Delta E$$

conservation law

$$\mathcal{L} \in \ker(S^T), \quad \mathcal{L}^T \mathbb{C} = \text{const.}$$

Biophysics I Lecture 2

Remark.

$$\frac{d}{dt} c = S J(c) \in \text{Im}(S).$$

$$\begin{aligned} \frac{d}{dt} (\ell^T c) &= \ell^T S J(c) \left(\begin{array}{l} \frac{d}{dt} \ell = 0 \\ \ell \in \text{ker}(S^T) \end{array} \right) \\ &= (S^T \ell) J(c) \\ &= 0 \end{aligned}$$



S : $n \times m$ matrix

o $\text{Im}(S) \perp \text{ker}(S^T)$

$$\left[\begin{array}{l} \text{Im}(S) = \{ S \phi \in \mathbb{R}^n \mid \phi \in \mathbb{R}^m \} \\ \text{ker}(S^T) = \{ x \in \mathbb{R}^n \mid S^T x = 0 \} \end{array} \right.$$

$$\underline{\mathbb{R}^n}$$



$$(\phi \in \mathbb{R}^m)$$

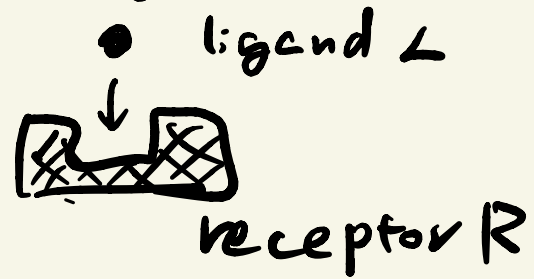
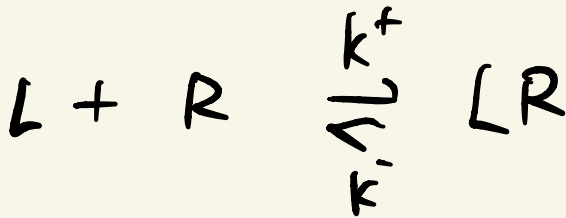
$$a \in \text{Im}(S) \rightarrow a = S \phi$$

$$b \in \text{ker}(S^T)$$

$$a^T b = (S \phi)^T b = \phi^T \underbrace{S^T b}_{= 0} = 0$$

Example 2

ligand-receptor binding.



Rate eq.

nonlinear!

$$\frac{d}{dt} C_L = -k^+ C_L C_R + k^- C_{LR} = -J(C)$$

$$\frac{d}{dt} C_R = -k^+ C_L C_R + k^- C_{LR} = -J(C)$$

$$\frac{d}{dt} C_{LR} = k^+ C_L C_R - k^- C_{LR} = +J(C)$$

$$C = \begin{pmatrix} C_L \\ C_R \\ C_{LR} \end{pmatrix}$$

$$S = \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}$$

L
R
LR

nonlinear function

$$\frac{d}{dt} C = S J(C)$$

L+R → LR

Ⓜ Ⓜ Ⓜ

3x1 matrix 3x1 matrix 1x1 matrix

$$\textcircled{1} \quad \text{rank}(\mathcal{S}) = 1$$

$$\dim(\ker(\mathcal{S}^T)) = 3 - 1 = 2.$$

$$\mathcal{S}^T = (-1 \quad -1 \quad 1)$$

$$\mathcal{L}^{(1)} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \in \ker(\mathcal{S}^T)$$

$$\mathcal{L}^{(2)} = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \in \ker(\mathcal{S}^T)$$

$$\Rightarrow \frac{d}{dt} (\mathcal{L}^{(1)T} \mathcal{C}) = 0$$

$$\textcircled{L} \quad \frac{d}{dt} (\underline{C}_L + \underline{C}_{LR}) = 0$$

$$\frac{d}{dt} (\mathcal{L}^{(2)T} \mathcal{C}) = 0$$

$$\textcircled{R} \quad \frac{d}{dt} (\underline{C}_R + \underline{C}_{LR}) = 0$$

- Probabilities.

$$\textcircled{1} \quad \frac{C_L}{C_L + C_{LR}}, \quad \frac{C_{LR}}{C_L + C_{LR}}$$

$$\textcircled{2} \quad \frac{C_R}{C_R + C_{LR}}, \quad \frac{C_{LR}}{C_R + C_{LR}}$$

② Equilibrium

$$J(C^{eq}) = 0$$

$$C^{eq} \in \mathbb{R}_{>0}^3$$

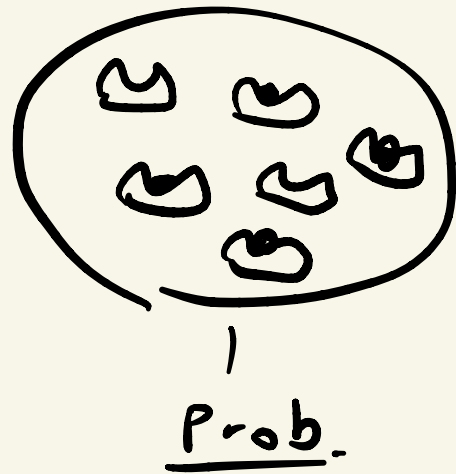
$$k^+ C_L^{eq} C_R^{eq} = k^- C_{LR}^{eq}$$

$$\frac{k^+}{k^-} = \frac{C_{LR}^{eq}}{C_L^{eq} C_R^{eq}}$$

[detailed balance
or
law of mass action

$$P_R^{eg} = \frac{C_R^{eg}}{C_R^{eg} + C_{LR}^{eg}}$$

$$P_{LR}^{eg} = \frac{C_{LR}^{eg}}{C_R^{eg} + C_{LR}^{eg}}$$

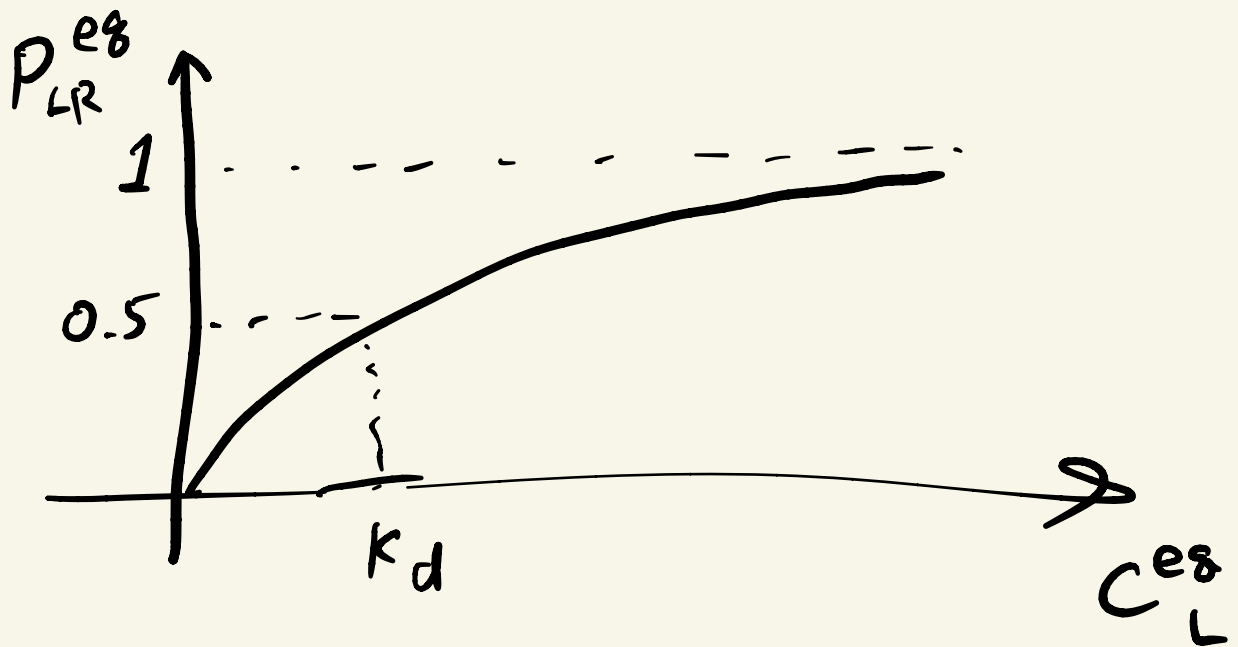


$$P_{LR}^{eg} = 1 - P_R^{eg}$$

$$= \frac{\frac{C_{LR}^{eg}}{C_R^{eg}}}{1 + \frac{C_{LR}^{eg}}{C_R^{eg}}}$$

$$= \frac{C_L^{eg} \frac{k^+}{k^-}}{1 + C_L^{eg} \frac{k^+}{k^-}} = \frac{\frac{C_L^{eg}}{K_d}}{1 + \frac{C_L^{eg}}{K_d}}$$

$K_d = \frac{k^-}{k^+}$: dissociation
constant

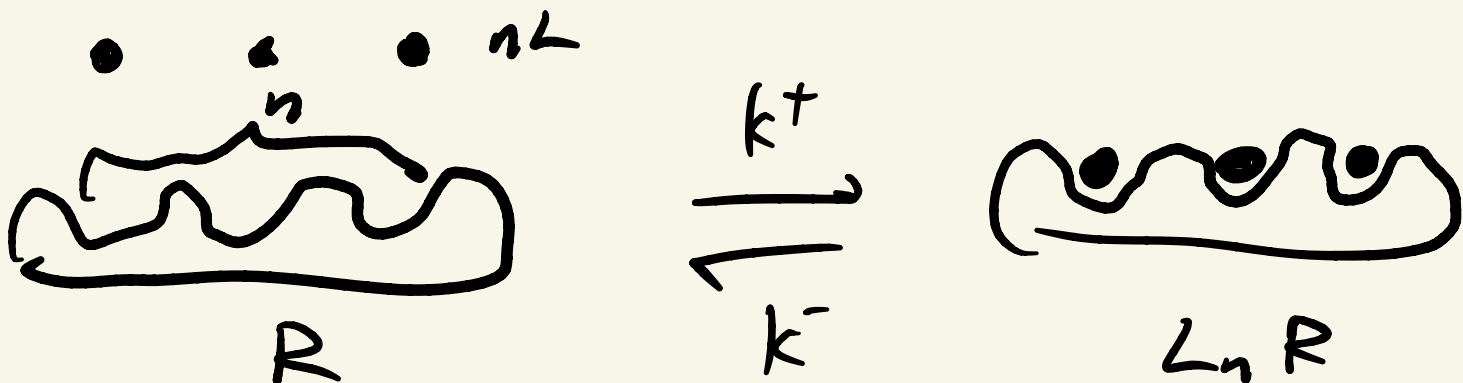


$$C_c^{es} = K_d$$

$$P_{LR}^{es} = \frac{\frac{K_d}{K_d}}{1 + \frac{K_d}{K_d}} = 0.5$$

Example 3

n ligand - 1 receptor



$$C = \begin{pmatrix} C_L \\ C_R \\ C_{L_n R} \end{pmatrix} \quad J(C) = k^+(C_L)^n C_R - k^- C_{L_n R}$$

$$S = \begin{pmatrix} -n \\ -1 \\ 1 \end{pmatrix} \begin{matrix} L \\ R \\ LR \end{matrix} \quad nL + R \rightarrow LR$$

\ominus
 \ominus
 \oplus

Rate eq.

$$\frac{d}{dt} C = S J(C)$$

$\underbrace{\hspace{2em}}$
 $\underbrace{\hspace{2em}}$
 $\underbrace{\hspace{2em}}$

3x1 matrix
3x1 matrix
1x1 matrix

①

$$\text{rank}(\mathcal{S}) = 1$$

$$\dim(\ker(\mathcal{S}^T)) = 3 - 1 = 2.$$

$$\mathbf{e}^{(1)} = \begin{pmatrix} 1 \\ 0 \\ n \end{pmatrix} \in \ker(\mathcal{S}^T)$$

$$\mathbf{e}^{(2)} = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \in \ker(\mathcal{S}^T)$$

$$\frac{d}{dt} ((\mathbf{e}^{(1)})^T \mathbf{c}) = 0$$

$$\rightarrow \frac{d}{dt} (c_L + n c_{L+nR}) = 0$$

$$\frac{d}{dt} ((\mathbf{e}^{(2)})^T \mathbf{c}) = 0$$

$$\rightarrow \frac{d}{dt} (c_R + c_{L+nR}) = 0$$

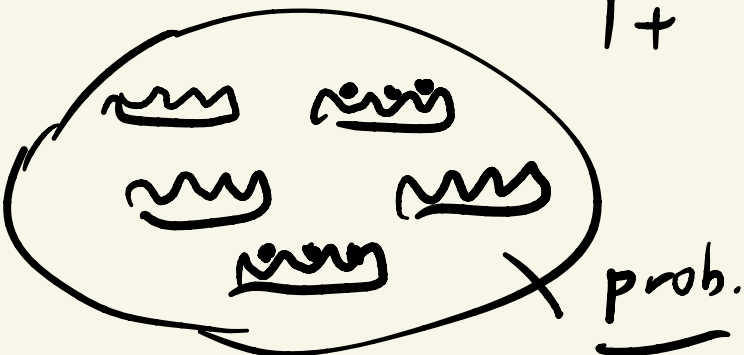
② Equilibrium

$$J(C^{eq}) = 0 \quad C^{eq} \in \mathbb{R}^3_{>0}$$

$$\frac{k^-}{k^+} = \frac{C_R^{eq} (C_L^{eq})^n}{C_{LnR}^{eq}}$$

$$\left[\begin{array}{l} p_R^{eq} = \frac{C_R^{eq}}{C_R^{eq} + C_{LnR}^{eq}} \\ p_{LnR}^{eq} = \frac{C_{LnR}^{eq}}{C_R^{eq} + C_{LnR}^{eq}} \end{array} \right.$$

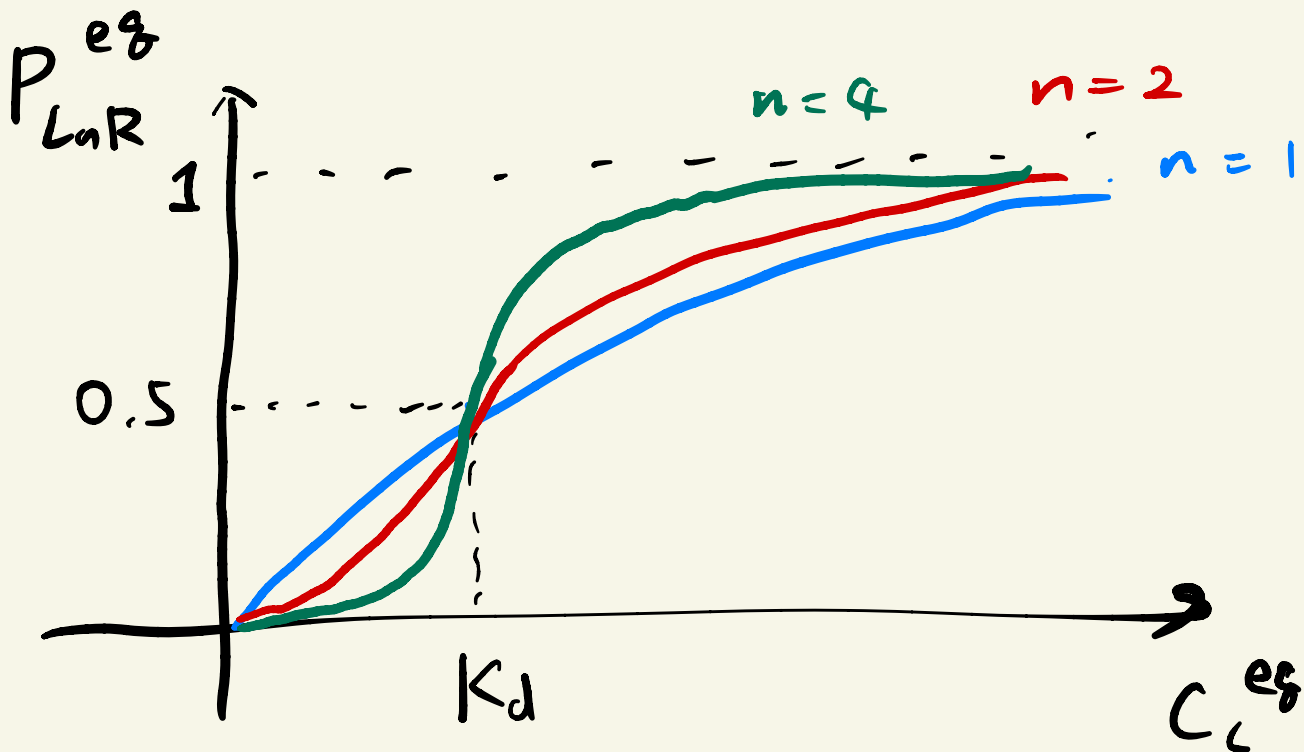
$$\begin{aligned} p_{LnR}^{eq} &= 1 - p_R^{eq} \\ &= \frac{C_{LnR}^{eq}}{C_R^{eq} + C_{LnR}^{eq}} = \frac{(C_L^{eq})^n \frac{k^+}{k^-}}{1 + (C_L^{eq})^n \frac{k^+}{k^-}} \end{aligned}$$



Hill equation

$$P_{LnR}^{eq} = \frac{\left(\frac{C_L^{eq}}{K_d}\right)^n}{1 + \left(\frac{C_L^{eq}}{K_d}\right)^n}$$

$$K_d = \left(\frac{k^-}{k^+}\right)^{\frac{1}{n}}$$



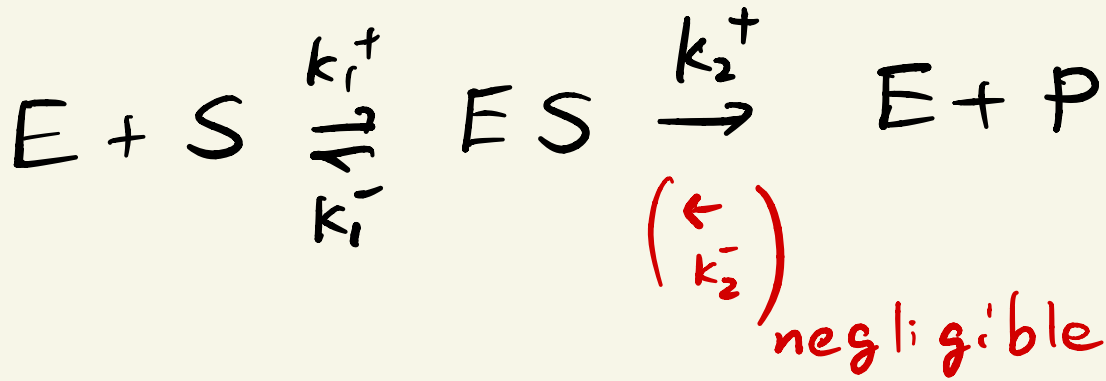
Allosteric
(Cooperative)

fitting parameter n
Hill coefficient

$$n \gg 1, \quad C_L^{eq} < K_d \rightarrow P_{LnR}^{eq} \sim 0$$

$$C_L^{eq} > K_d \rightarrow P_{LnR}^{eq} \sim 1$$

Example 4 = Enzyme reaction



- E: Enzyme
- S: Substrate
- P: product
- ES: Enzyme-substrate complex.

Rate eq. 4x2 matrix 2x1 matrix

$$\frac{d}{dt} \mathbf{C} = \mathbf{S} \mathbf{J}(\mathbf{C})$$

$$\mathbf{C} = \begin{pmatrix} C_E \\ C_S \\ C_{ES} \\ C_P \end{pmatrix}$$

$$\mathbf{S} = \begin{pmatrix} -1 & 1 \\ -1 & 0 \\ 1 & -1 \\ 0 & 1 \end{pmatrix}$$

$$\mathbf{J}(\mathbf{C}) = \begin{pmatrix} J_1(\mathbf{C}) \\ J_2(\mathbf{C}) \end{pmatrix}$$

$$J_1(\mathbf{C}) = k_i^+ C_E C_S - k_i^- C_{ES}, \quad J_2(\mathbf{C}) = k_2^+ C_{ES}$$

$$\textcircled{1} \quad \text{rank}(\mathcal{S}) = 2$$

$$\dim(\ker(\mathcal{S}^T)) = 4 - 2 = 2.$$

$$\mathcal{S}^T = \begin{pmatrix} -1 & -1 & 1 & 0 \\ 1 & 0 & -1 & 1 \end{pmatrix}$$

$$\mathcal{Q}^{(1)} = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \in \ker(\mathcal{S}^T)$$

$$\mathcal{Q}^{(2)} = \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} \in \ker(\mathcal{S}^T)$$

$$\frac{d}{dt} ((\mathcal{Q}^{(1)})^T \mathcal{C}) = 0$$

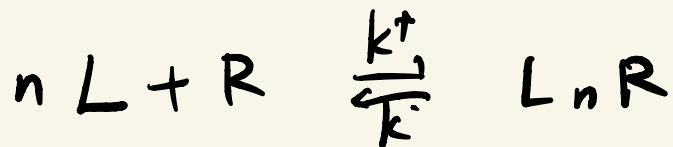
$$\rightarrow \frac{d}{dt} (\underline{C}_E + \underline{C}_{ES}) = 0 \quad \textcircled{E}$$

$$\frac{d}{dt} ((\mathcal{Q}^{(2)})^T \mathcal{C}) = 0$$

$$\rightarrow \frac{d}{dt} (\underline{C}_S + \underline{C}_{ES} + \underline{C}_P) = 0 \quad \textcircled{S \text{ or } P}$$

Summary

• ligand - receptor binding

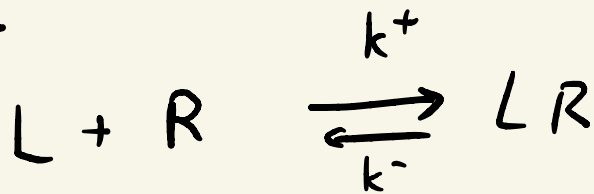


$$P_{L_n R}^{es} = \frac{\left(\frac{C_L^{es}}{K_d}\right)^n}{1 + \left(\frac{C_L^{es}}{K_d}\right)^n}$$

Hill equation

Bio physics I Lecture 3

Remark



$$p_{LR}^{eq} = \frac{C_{LR}^{eq}}{C_R^{eq} + C_{LR}^{eq}}$$

$$= \frac{C_L^{eq} \frac{k^+}{k^-}}{1 + C_L^{eq} \frac{k^+}{k^-}}$$

Grand Canonical

distribution

(N=0)

(N=1)

R

LR



particle bath

μ_L^{eq}

$$p_{LR}^{eq} = \frac{\exp(-\beta(\epsilon_{LR} - \epsilon_R - \mu_L^{eq}))}{1 + \exp(-\beta(\epsilon_{LR} - \epsilon_R - \mu_L^{eq}))}$$

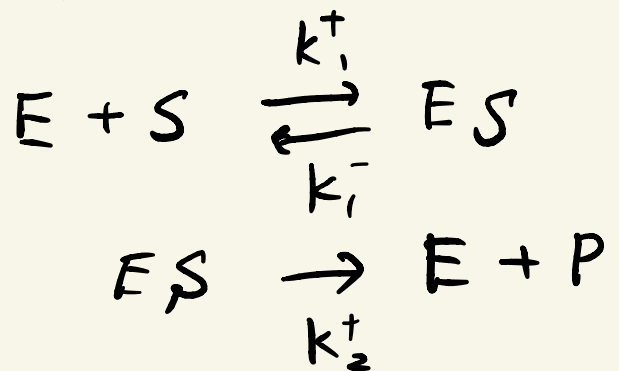
$$\Rightarrow \ln\left(C_L^{eq} \frac{k^+}{k^-}\right) = -\beta(\epsilon_{LR} - \epsilon_R - \mu_L^{eq})$$

local detailed balance

$$\ln \frac{k^+}{k^-} = -\beta (E_{LR} - E_R - E_L)$$

• $\mu_L^{eg} = E_L + \beta^{-1} \ln C_L^{eg}$
Chemical potential

Example 4: Enzyme reaction



(2) Assumption

$$\frac{d}{dt} C_{ES} = J_1(C^*) - J_2(C^*) \cong 0$$

$$k_1^+ C_E^* C_S^* - k_1^- C_{ES}^* - k_2^+ C_{ES}^* = 0$$

$$C_{Etot} = C_E^* + C_{ES}^* = \text{const.}$$

$$C_{ES}^* = \frac{k_1^+ C_{Etot} C_S^*}{k_2^+ + k_1^- + k_1^+ C_S^*}$$

$$\begin{aligned}
 \frac{d}{dt} C_P &= k_2^+ C_{ES}^* \\
 &= k_2^+ C_{E_{tot}} \frac{\frac{k_1^+}{k_1^- + k_2^+} C_S^*}{1 + \frac{k_1^+}{k_1^- + k_2^+} C_S^*} \\
 &= V_{max} \frac{\frac{C_S^*}{K_m}}{1 + \frac{C_S^*}{K_m}} \quad \text{Michaelis-Menten equation}
 \end{aligned}$$

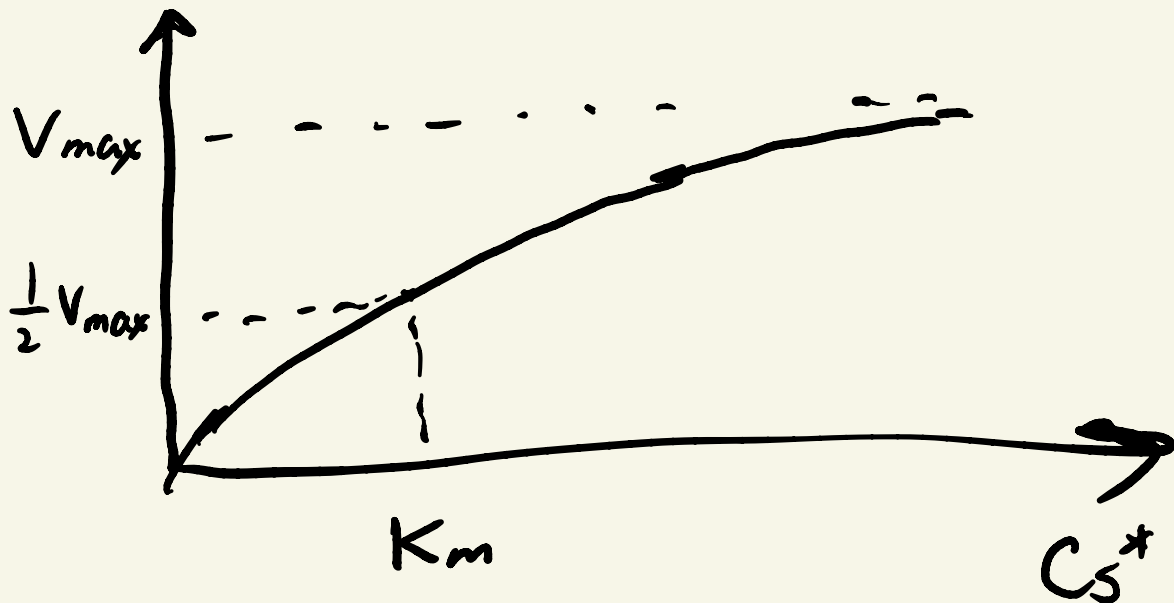
Michaelis constant

$$K_m = \frac{k_1^- + k_2^+}{k_1^+}$$

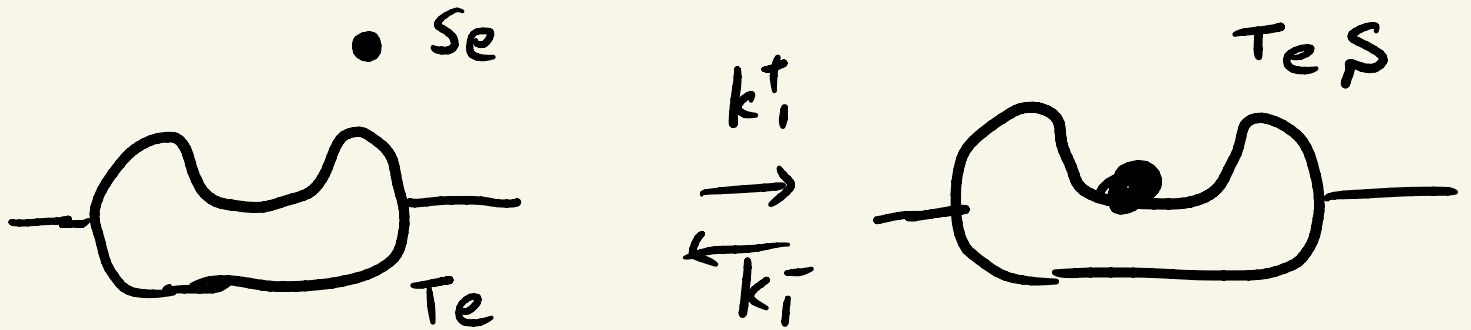
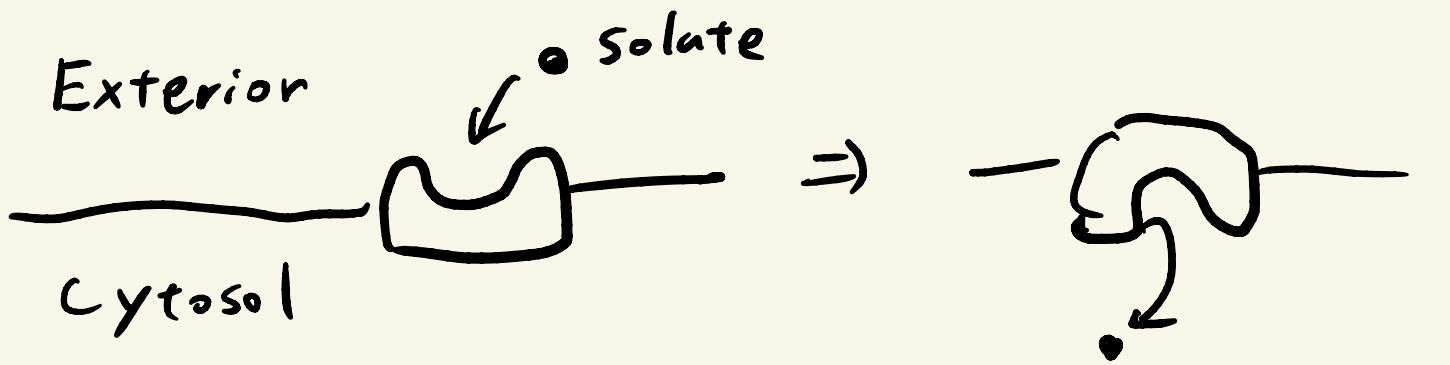
limiting rate

$$V_{max} = k_2^+ C_{E_{tot}}$$

$$\frac{dC_P}{dt}$$

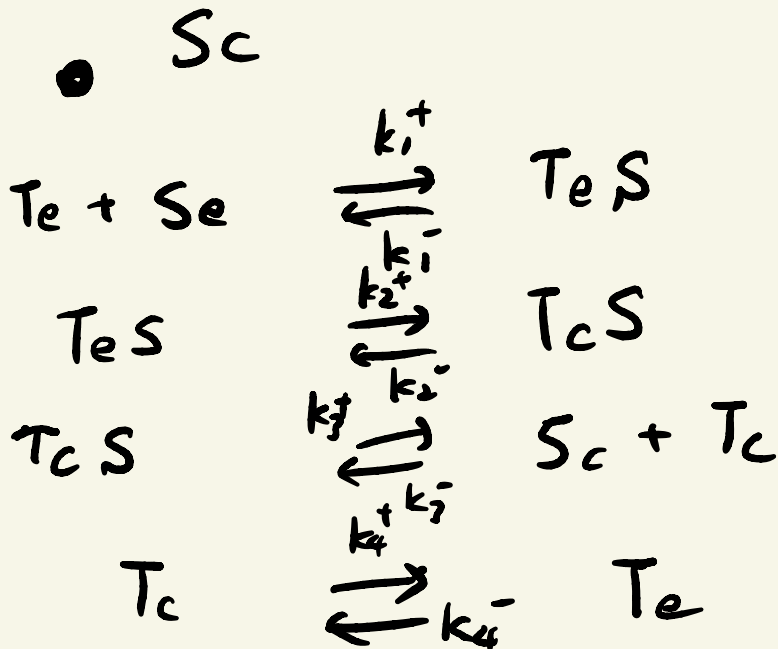
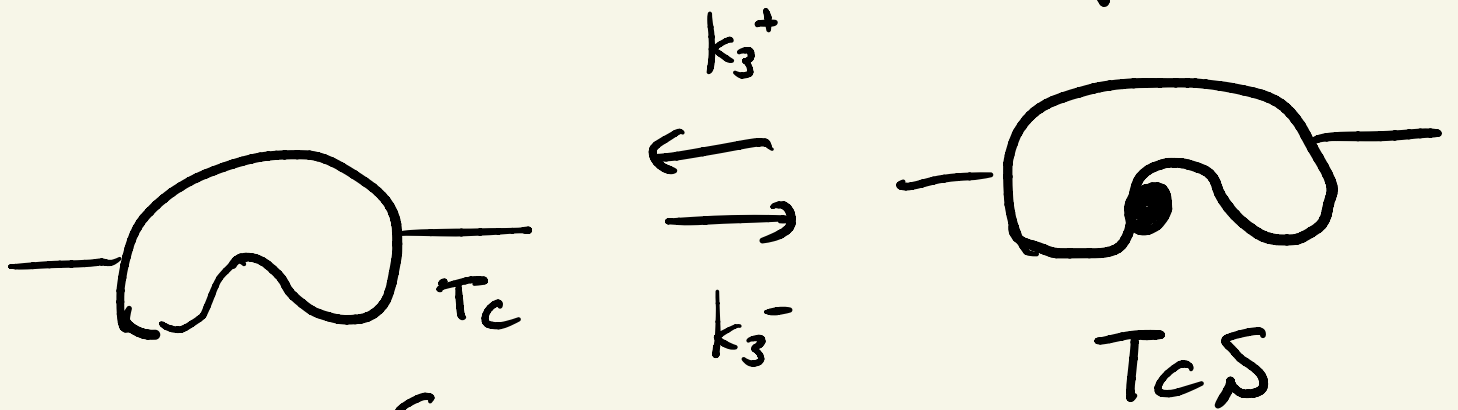


Example 5: Membrane transport



k_4^- ↓ ↑ k_4^+

k_2^+ ↓ ↑ k_2^-



$$\mathbb{C} = \begin{pmatrix} C_{Te} \\ C_{Tc} \\ C_{TeS} \\ C_{TcS} \\ C_{Se} \\ C_{Sc} \end{pmatrix} \quad \mathbb{J}(\mathbb{C}) = \begin{pmatrix} J_1(\mathbb{C}) \\ J_2(\mathbb{C}) \\ J_3(\mathbb{C}) \\ J_4(\mathbb{C}) \end{pmatrix}$$

$$J_1(\mathbb{C}) = k_1^+ C_{Te} C_{Se} - k_1^- C_{TeS}$$

$$J_2(\mathbb{C}) = k_2^+ C_{TeS} - k_2^- C_{TcS}$$

$$J_3(\mathbb{C}) = k_3^+ C_{TcS} - k_3^- C_{Sc} C_{Tc}$$

$$J_4(\mathbb{C}) = k_4^+ C_{Tc} - k_4^- C_{Te}$$

$$\frac{d}{dt} \mathbb{C} = \underbrace{\begin{pmatrix} -1 & 0 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}}_{\mathbb{S}} \mathbb{J}(\mathbb{C})$$

$$\textcircled{1} \text{ rank}(\mathbb{S}) = 4$$

$$\dim(\ker(\mathbb{S}^T)) = 6 - 4 = 2$$

$$S^T = \begin{pmatrix} -1 & 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & -1 & -1 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$S^T \begin{pmatrix} 1 \\ \vdots \\ 0 \end{pmatrix} = 0 \quad \begin{pmatrix} \vdots \\ 0 \end{pmatrix} \in \ker(S^T)$$

$$S^T \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix} = 0 \quad \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix} \in \ker(S^T)$$

$$\frac{d}{dt} (C_{Te} + C_{Tc} + C_{TeS} + C_{TcS}) = 0 \quad \textcircled{T}$$

$$\frac{d}{dt} (C_{TeS} + C_{TcS} + C_{Sc} + C_{Se}) = 0 \quad \textcircled{S}$$

② Equilibrium

$$J(Q^{eq}) = 0$$

$$Q^{eq} \in \mathbb{R}_{>0}^6$$

$$\frac{k_1^+}{k_1^-} = \frac{C_{TeS}^{e\delta}}{C_{Te}^{e\delta} C_{Se}^{e\delta}}, \quad \frac{k_2^+}{k_2^-} = \frac{C_{TeS}^{e\delta}}{C_{TeS}^{e\delta}}$$

$$\frac{k_3^+}{k_3^-} = \frac{C_{Sc}^{e\delta} C_{Tc}^{e\delta}}{C_{TcS}^{e\delta}}, \quad \frac{k_4^+}{k_4^-} = \frac{C_{Tc}^{e\delta}}{C_{Te}^{e\delta}}$$

law of mass action

Check

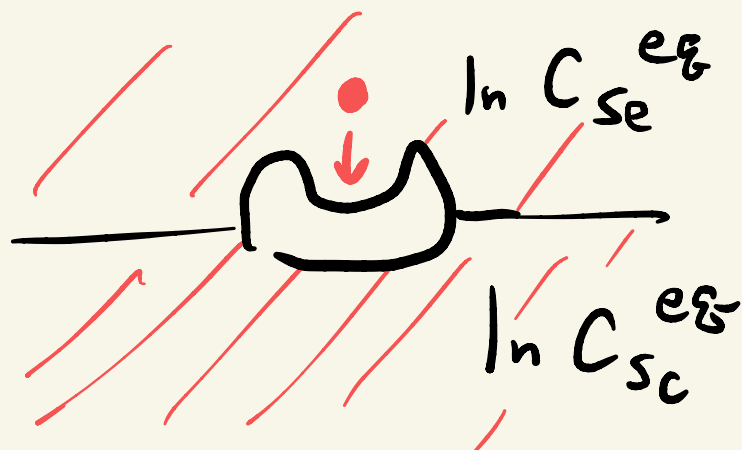
$$\frac{C_{Sc}^{e\delta}}{C_{Se}^{e\delta}} = \frac{k_1^+ k_2^+ k_3^+ k_4^+}{k_1^- k_2^- k_3^- k_4^-}$$

$$\text{or } \ln \frac{k_1^+ k_2^+ k_3^+ k_4^+}{k_1^- k_2^- k_3^- k_4^-} = \ln C_{Sc}^{e\delta} - \ln C_{Se}^{e\delta}$$

• Energy difference

(local detailed balance)

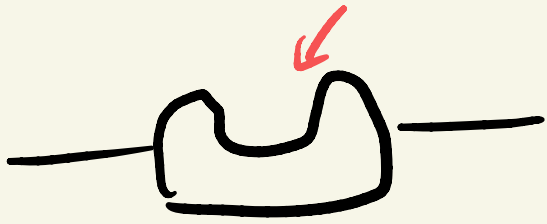
• Chemical potential difference



③ Open system

C_{se}

J^{ex}



$$\begin{cases} \frac{d}{dt} C_{se} = 0 \\ \frac{d}{dt} C_{sc} = 0 \end{cases}$$

C_{sc}

J^{ex}

Chemostat.

$$\frac{d}{dt} \mathbb{C} = \underbrace{\begin{pmatrix} -1 & 0 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}}_{\mathbb{A}^2} \mathbb{J}(\mathbb{C})$$

$$\mathbb{J}^{ex}(\mathbb{C}) = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \end{pmatrix} \mathbb{J}(\mathbb{C})$$

$$\frac{d}{dt} \mathbb{C} = \tilde{\mathbb{A}} \mathbb{J}(\mathbb{C}) = \mathbb{A} \mathbb{J}(\mathbb{C}) + \mathbb{J}^{ex}(\mathbb{C})$$

$$\text{rank}(\tilde{\mathcal{S}}) = 3 \quad !$$

$$\dim(\ker(\tilde{\mathcal{S}}^T)) = 6 - 3 = 3$$

$$\dim(\ker(\tilde{\mathcal{S}})) = 4 - 3 = 1 \quad !$$

$$\mathcal{S}^T = \begin{pmatrix} -1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\mathcal{S}^T \begin{pmatrix} 1 \\ \vdots \\ 0 \end{pmatrix} = \mathbf{0} \quad \frac{d}{dt}(C_{TeS} + C_{TcS} + C_{Te} + C_{Tc}) = 0$$

$$\mathcal{S}^T \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \mathbf{0} \quad \frac{d}{dt} C_{Se} = 0$$

$$\mathcal{S}^T \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ -1 \end{pmatrix} = \mathbf{0} \quad \frac{d}{dt} C_{Sc} = 0$$

$$\textcircled{3} \quad \mathcal{S}^2 \begin{pmatrix} | \\ | \\ | \\ | \\ | \end{pmatrix} = \begin{pmatrix} -1 & 0 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} | \\ | \\ | \\ | \end{pmatrix} = \mathbf{0}$$

$$\begin{pmatrix} | \\ | \\ | \\ | \end{pmatrix} \in \ker(\tilde{\mathcal{S}})$$

$$\frac{d}{dt} \mathbf{c} = \tilde{\mathcal{S}} \mathcal{J}(\mathbf{c})$$

$$\mathcal{J}(\mathbf{c}^{st}) = \alpha \begin{pmatrix} | \\ | \\ | \\ | \end{pmatrix} \in \ker(\tilde{\mathcal{S}})$$

$$(\alpha \neq 0, \alpha \in \mathbb{R})$$

$$\begin{aligned} \frac{d}{dt} \mathbf{c}^{st} &= \tilde{\mathcal{S}} \mathcal{J}(\mathbf{c}^{st}) \\ &= \alpha \tilde{\mathcal{S}} \begin{pmatrix} | \\ | \\ | \\ | \end{pmatrix} = \mathbf{0} \end{aligned}$$

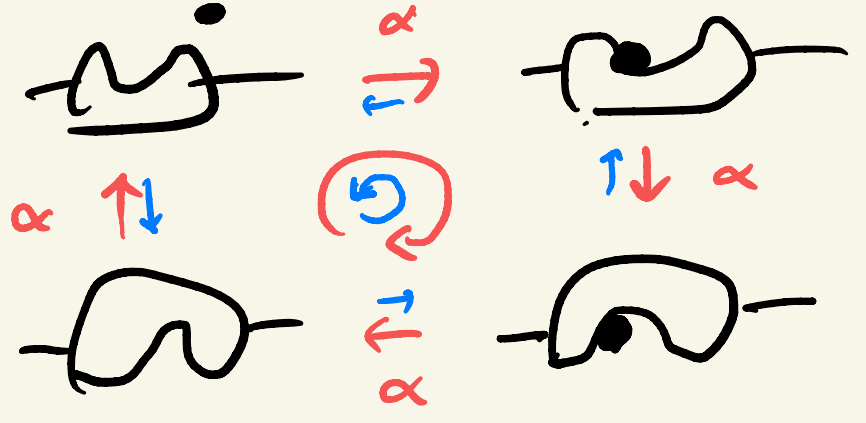
\mathbf{c}^{st} : non-equilibrium steady state

$$J_1(\mathbb{C}) = \alpha$$

$$J_2(\mathbb{C}) = \alpha$$

$$J_3(\mathbb{C}) = \alpha$$

$$J_4(\mathbb{C}) = \alpha$$



ker(S)

cycle!

cf.) Electromagnetics

$$\nabla \cdot \mathbb{B} = 0$$

$$\rightarrow \nabla \times \mathbb{A} = \mathbb{B} \quad \text{rotation}$$

$$\mathbb{S} \cdot \mathbb{J} = 0$$

\mathbb{J} : cycle .

$$\mathbb{S} \leftarrow \dots \rightarrow \begin{matrix} -\nabla \cdot \\ -\text{div} \end{matrix}$$

$$\left(\mathbb{S}^T \left\langle \dots \dots \right\rangle \nabla \right) \text{grad}$$

$\alpha = 0$ equilibrium .

$\alpha > 0$

or

$\alpha < 0$

2nd law of thermodynamics

⑤ 2nd law of thermodynamics

$$J_i(\mathcal{C}) = \frac{J_i^+(\mathcal{C})}{\geq 0} - \frac{J_i^-(\mathcal{C})}{\geq 0}$$

e.g.) $J_i(\mathcal{C}) = \frac{k_i^+ C_{Te} C_{Tse}}{J_i^+(\mathcal{C})} - \frac{k_i^- C_{Te} S}{J_i^-(\mathcal{C})}$

$$F_i(\mathcal{C}) = \ln \frac{J_i^+(\mathcal{C})}{J_i^-(\mathcal{C})}$$

$J_i(\mathcal{C}), F_i(\mathcal{C})$: same sign.

$$\left(\begin{array}{l} J_i(\mathcal{C}) > 0, F_i(\mathcal{C}) > 0 \quad (J_i^+(\mathcal{C}) > J_i^-(\mathcal{C})) \\ J_i(\mathcal{C}) = 0, F_i(\mathcal{C}) = 0 \quad (J_i^+(\mathcal{C}) = J_i^-(\mathcal{C})) \\ J_i(\mathcal{C}) < 0, F_i(\mathcal{C}) < 0 \quad (J_i^+(\mathcal{C}) < J_i^-(\mathcal{C})) \end{array} \right.$$

$$\Rightarrow J_i(\mathcal{C}) F_i(\mathcal{C}) \geq 0$$

• Entropy production rate

$$\sigma(\mathcal{C}) = \sum_i J_i(\mathcal{C}) F_i(\mathcal{C}) \underline{\geq 0}$$

2nd law of thermodynamics

• $C = C^{eq} \quad J(C) = 0$
 $(F(C^{eq}) = 0)$

$\sigma(C^{eq}) = 0 \quad \text{equilibrium}$

• $C \neq C^{eq}, \quad J(C) \neq 0$

$\sigma(C) > 0 \quad \text{non-equilibrium}$

Entropy change

$$\textcircled{F_i} = \ln \frac{k_i^+ C_{Te} C_{Se}}{k_i^- C_{TeS}}$$

energy change

chemical potential change

(local detailed balance)

Entropy production rate

$$\sigma(C) = \sum_i \underbrace{F_i(C)}_{\text{entropy change}} \underbrace{J_i(C)}_{\text{flow}}$$

$$J(C^{st}) = \begin{pmatrix} \alpha \\ \alpha \\ \alpha \\ \alpha \end{pmatrix} \quad \alpha \neq 0$$

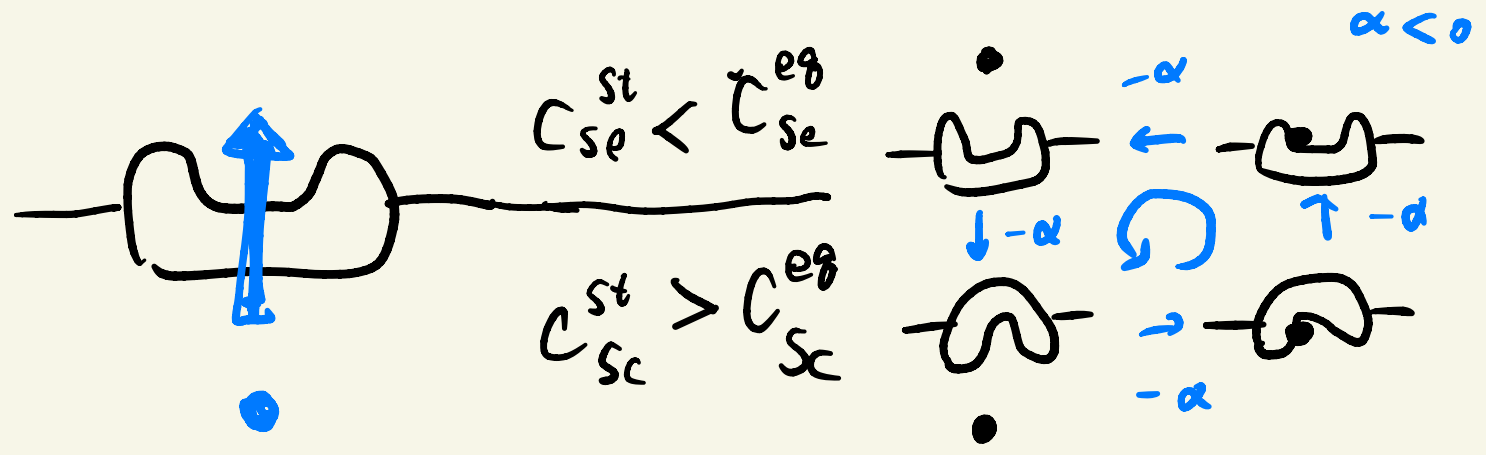
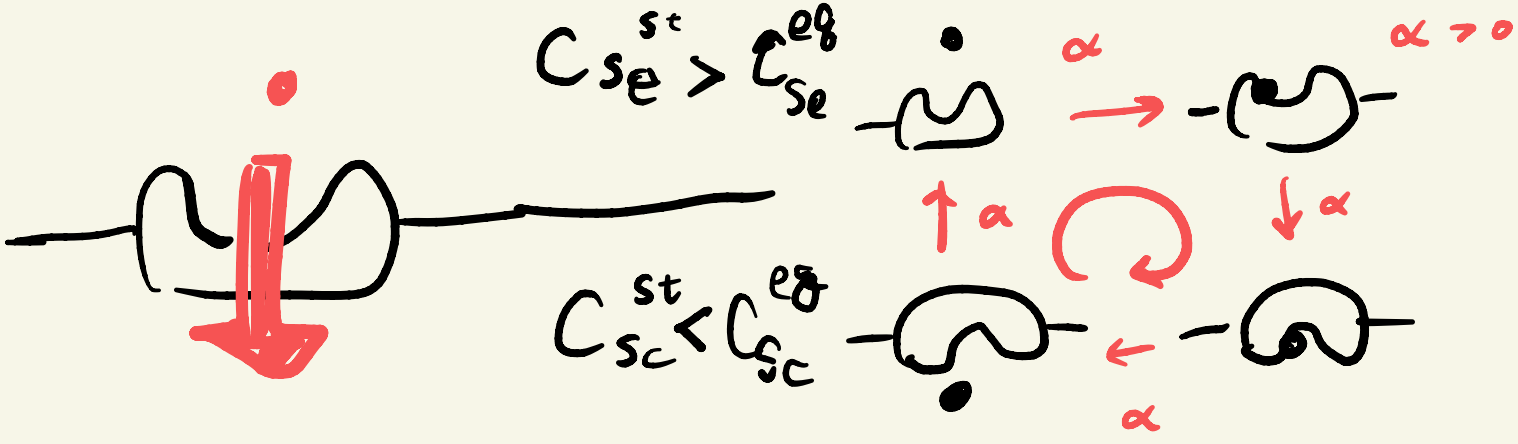
$$\begin{aligned} \sigma(C^{st}) &= \sum_i J_i(C^{st}) F_i(C^{st}) \\ &= \alpha \sum_i F_i(C^{st}) \\ &= \alpha \ln \frac{k_1^+ k_2^+ k_3^+ k_4^+ C_{Se}^{st}}{k_1^- k_2^- k_3^- k_4^- C_{Sc}^{st}} \\ &= \alpha \left(\ln \frac{C_{Se}^{st}}{C_{Sc}^{st}} - \ln \frac{C_{Se}^{eq}}{C_{Sc}^{eq}} \right) \stackrel{?}{=} 0 \end{aligned}$$

2nd law
($\alpha \neq 0, \sigma(C^{st}) > 0$)

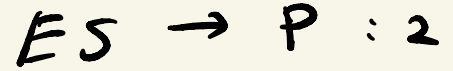
$$\frac{C_{Se}^{st}}{C_{Sc}^{st}} > \frac{C_{Se}^{eq}}{C_{Sc}^{eq}} \Rightarrow \alpha > 0$$

$$\frac{C_{Se}^{st}}{C_{Sc}^{st}} < \frac{C_{Se}^{eq}}{C_{Sc}^{eq}} \Rightarrow \alpha < 0$$

$$\left(\frac{C_{Se}^{st}}{C_{Sc}^{st}} = \frac{C_{Se}^{eq}}{C_{Sc}^{eq}} \Rightarrow \alpha = 0 \text{ (equilibrium)} \right)$$



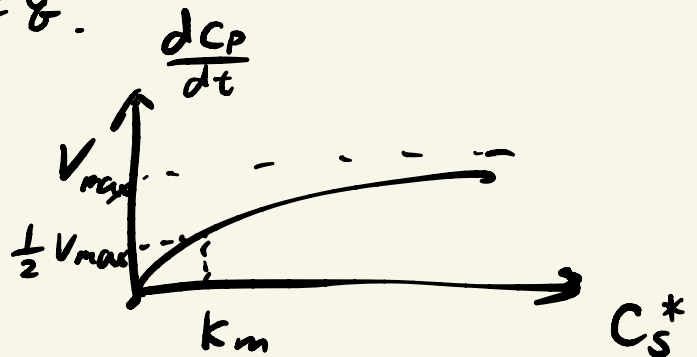
Summary



$J_1(c^*) - J_2(c^*) \approx 0$

$$\frac{d}{dt} c_p = v_{max} \frac{\frac{c_s^*}{K_m}}{1 + \frac{c_s^*}{K_m}}$$

Michaelis - Menten Eq.



Open system

$$\frac{d}{dt} c = \tilde{S} J(c) = S J(c) + J^{ex}(c)$$

$\text{Ker}(\tilde{S}) : \text{cycle}$

Entropy production rate

$$\sigma(c) = \sum_i J_i(c) F_i(c) (\geq 0 \text{ 2nd law})$$

$$J_i(c) = J_i^+(c) - J_i^-(c)$$

$$F_i(c) = \ln \frac{J_i^+(c)}{J_i^-(c)}$$

Biophysics I Lecture 4

Remark

$$\sigma(\mathcal{C}) = \sum_i F_i(\mathcal{C}) J_i(\mathcal{C}) \geq 0$$

$$\forall i, F_i(\mathcal{C}^{eq}) = 0$$

$$\Leftrightarrow \forall i, J_i(\mathcal{C}^{eq}) = 0$$

$$J_i(\mathcal{C}^{st}) = \begin{pmatrix} \alpha \\ \alpha \\ \alpha \\ \alpha \end{pmatrix}$$

$$\sigma(\mathcal{C}^{st}) = \alpha \sum_i F_i(\mathcal{C}^{st})$$

$$\alpha = 0 \Rightarrow \forall i, J_i(\mathcal{C}^{st}) = 0$$




$$\Rightarrow \forall i, F_i(\mathcal{C}^{st}) = 0$$

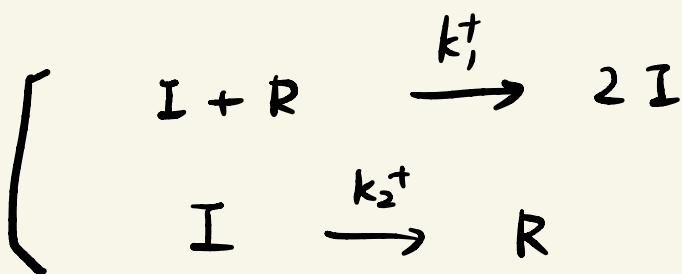
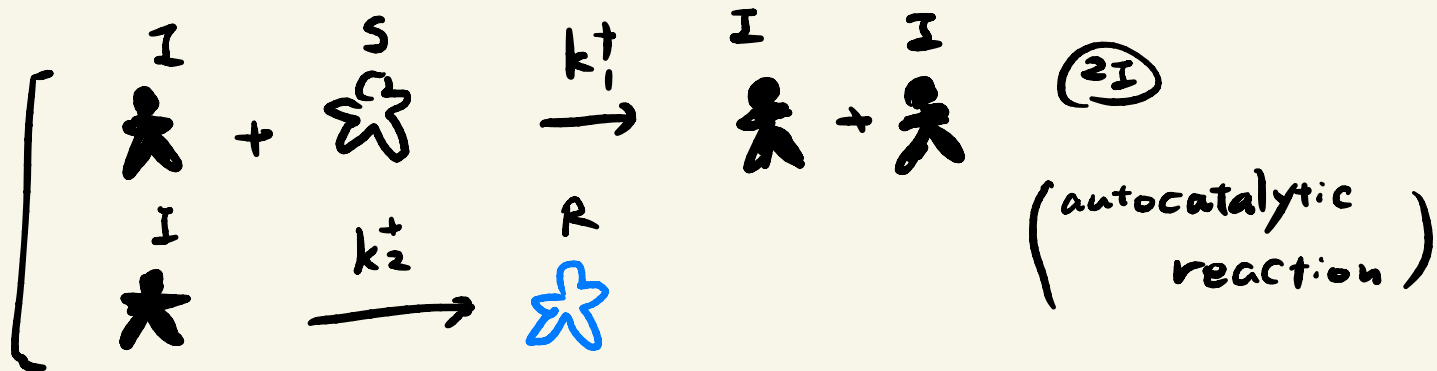
$$\Rightarrow \sum_i F_i(\mathcal{C}^{st}) = 0$$

Thus,

$$\alpha = 0 \Rightarrow \sum_i F_i(\mathcal{C}^{st}) = 0$$

Example 6: SIR model

- Susceptible S 
- Infected I 
- Recovered R 



$$\mathbf{C} = \begin{pmatrix} C_S \\ C_I \\ C_R \end{pmatrix}$$

$$J_1(\mathbf{C}) = k_1^+ C_I C_S$$

$$J_2(\mathbf{C}) = k_2^+ C_I$$

$$\frac{d}{dt} \mathbf{C} = \underbrace{\begin{pmatrix} -1 & 0 \\ 1 & -1 \\ 0 & 1 \end{pmatrix}}_J \mathbf{C}, \quad \mathbf{J}(\mathbf{C}) = \begin{pmatrix} J_1(\mathbf{C}) \\ J_2(\mathbf{C}) \end{pmatrix}$$

$$\textcircled{1} \quad \text{Rank}(S) = 2$$

$$\dim(\ker(S^T)) = 3 - 2 = 1$$

$$S^T = \begin{pmatrix} -1 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix}$$

$$S^T \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = 0 \quad \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \in \ker(S^T)$$

$$\Rightarrow \frac{d}{dt}(C_S + C_I + C_R) = 0$$

$$N = C_S + C_I + C_R.$$

$$\textcircled{2} \quad \begin{aligned} \frac{d}{dt} C_I &= J_1(\mathcal{C}) - J_2(\mathcal{C}) \\ &= (k_1^+ C_S - k_2^+) C_I \end{aligned}$$

$$k_1^+ C_S - k_2^+ < 0, \quad \frac{d}{dt} C_I < 0$$

$$R_0 C_S = \frac{k_1^+}{k_2^+} C_S < 1$$

$R_0 = \frac{k_1^+}{k_2^+}$: basic number
of reproduction

③ Steady state.

$$J(C^{st}) = 0 \quad \rightarrow \quad C_I^{st} = 0$$

$$C_S^{st} = N - C_R^{st}$$

additional conservation law

$$\frac{d}{dt} C_S = -k_1^+ C_I C_S$$

$$\frac{d}{dt} C_R = k_2^+ C_I$$

$$\rightarrow \frac{d}{dt} C_S = -\frac{k_1^+}{k_2^+} C_S \frac{d}{dt} C_R$$

$$\rightarrow \frac{d}{dt} (\ln C_S + R_0 C_R) = 0$$

$$\ln C_S + R_0 C_R = \text{const.}$$

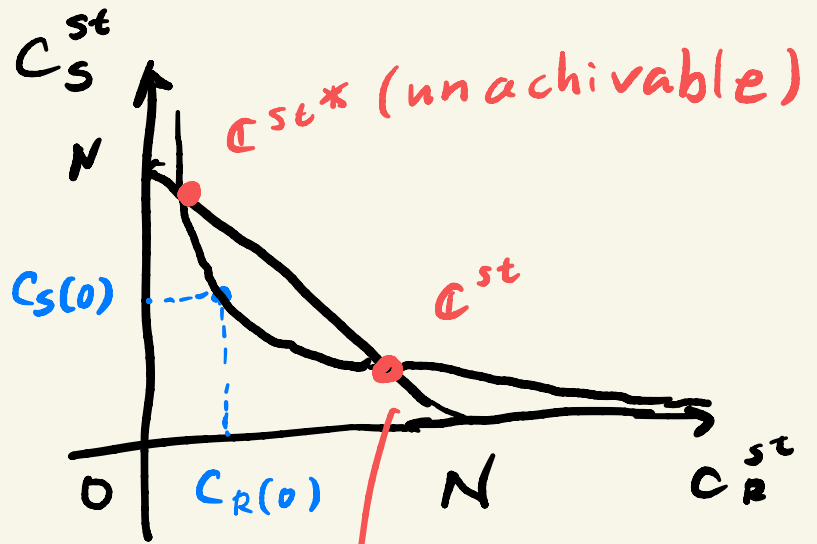
$C_S(0), C_R(0)$: C_S and C_R at time $t=0$

$$\ln C_S^{st} + R_0 C_R^{st} = \ln C_S(0) + R_0 C_R(0)$$

$$\Rightarrow C_S^{st} = C_S(0) \exp\left[R_0 [C_R(0) - C_R^{st}]\right]$$

$$C_S^{st} = N - C_R^{st}$$

$$C_S^{st} = C_S(0) \exp[k_0(C_R(0) - C_R^{st})]$$

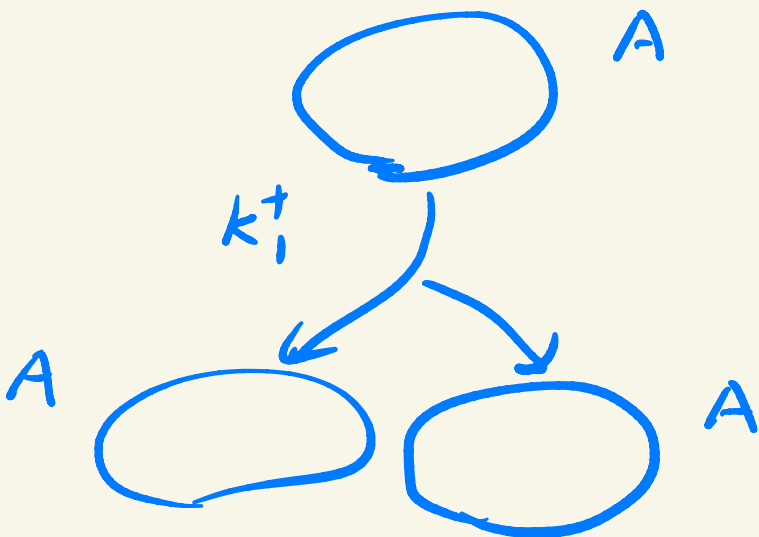


$$\left(\begin{array}{l} C_S(0) \geq 0 \\ \rightarrow C_S(0) + C_R(0) \leq N \end{array} \right)$$

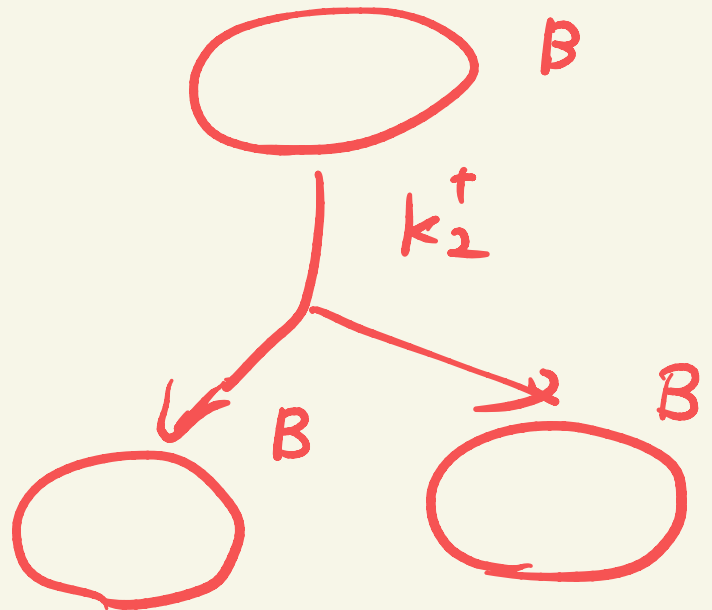
$$\frac{d}{dt} C_R \geq 0 \rightarrow \text{achievable steady state}$$

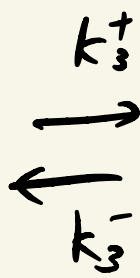
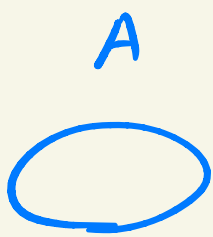
Example 7: Cell differentiation

type A

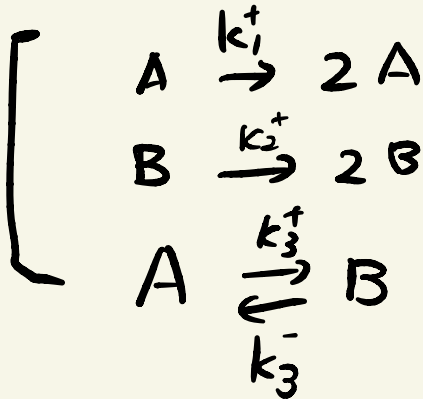


type B





mutation



Rate eq.

$$\mathbf{C} = \begin{pmatrix} C_A \\ C_B \end{pmatrix}$$

$$\mathbf{J}(\mathbf{C}) = \begin{pmatrix} k_1^+ C_A \\ k_2^+ C_B \\ k_3^+ C_A - k_3^- C_B \end{pmatrix}$$

$$\frac{d}{dt} \mathbf{C} = \underbrace{\begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \end{pmatrix}}_{\mathbf{S}} \mathbf{J}(\mathbf{C})$$

$$\textcircled{1} \quad \text{rank}(\mathcal{S}) = 2$$

$$\dim(\ker(\mathcal{S}^T)) = 2 - 2 = 0$$

$$\dim(\ker(\mathcal{S})) = 3 - 2 = 1$$

$$\begin{pmatrix} / & 0 & -/ \\ 0 & / & / \end{pmatrix} \begin{pmatrix} / \\ -/ \\ / \end{pmatrix} = \mathbb{0}$$

$$\begin{pmatrix} \alpha \\ -\alpha \\ \alpha \end{pmatrix} \in \ker(\mathcal{S})$$

$$\mathcal{J}(\mathbb{C}^{st}) = \begin{pmatrix} \alpha \\ -\alpha \\ \alpha \end{pmatrix} \quad (\alpha \neq 0)$$

is not achievable !

$$\mathcal{J}_1(\mathbb{C}) \geq 0$$

$$\rightarrow \alpha = 0$$

$$\mathcal{J}_2(\mathbb{C}) \geq 0$$

②

$$P_A = \frac{C_A}{C_A + C_B}$$

$$P_B = \frac{C_B}{C_A + C_B}$$

Remark

$$\frac{d}{dt}(C_A + C_B) \neq 0$$

$$[\dim(\ker(S^T)) = 0]$$

Notation

$$k_1^+ = \lambda_A$$

$$k_2^+ = \lambda_B$$

$$k_3^+ = W_{BA}$$

$$k_3^- = W_{AB}$$

↳

$$\frac{d}{dt} P_A = \frac{1}{C_A + C_B} \frac{d}{dt} C_A + C_A \frac{d}{dt} \left(\frac{1}{C_A + C_B} \right)$$

$$= \lambda_A P_A + W_{AB} P_B - W_{BA} P_A$$

$$- P_A (\lambda_A P_A + \lambda_B P_B)$$

(non linear

master Eq.)

Expected value $\langle \lambda \rangle = \lambda_A P_A + \lambda_B P_B$

$$\frac{d}{dt} P_A = (\lambda_A - \langle \lambda \rangle) P_A + W_{AB} P_B - W_{BA} P_A$$

For P_B

$$\frac{d}{dt} P_B = (\lambda_B - \langle \lambda \rangle) P_B + W_{BA} P_A - W_{AB} P_B$$

$$IP = \begin{pmatrix} P_A \\ P_B \end{pmatrix} \quad \tilde{J}(IP) = \begin{pmatrix} (\lambda_A - \langle \lambda \rangle) P_A \\ (\lambda_B - \langle \lambda \rangle) P_B \\ W_{BA} P_A - W_{AB} P_B \end{pmatrix}$$

$$\frac{d}{dt} IP = \underbrace{\begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \end{pmatrix}}_{\text{Same } \mathcal{S} \text{ ?}} \tilde{J}(IP)$$

Same \mathcal{S} ?

$$\tilde{J}(IP^{sb}) = \begin{pmatrix} \alpha \\ -\alpha \\ \alpha \end{pmatrix} \in \ker(\mathcal{S})$$

achievable !

$$\frac{d}{dt} P^{st} = \mathcal{S} \tilde{J}(P^{st}) = \mathcal{S} \begin{pmatrix} \alpha \\ -\alpha \\ \alpha \end{pmatrix} = 0$$

"steady" - state.

check.

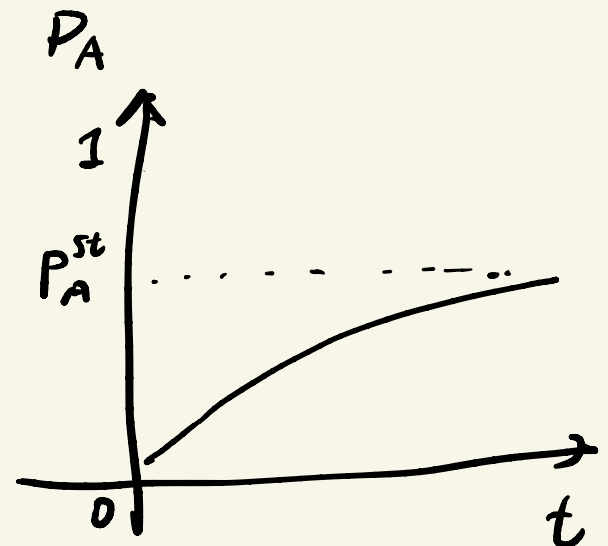
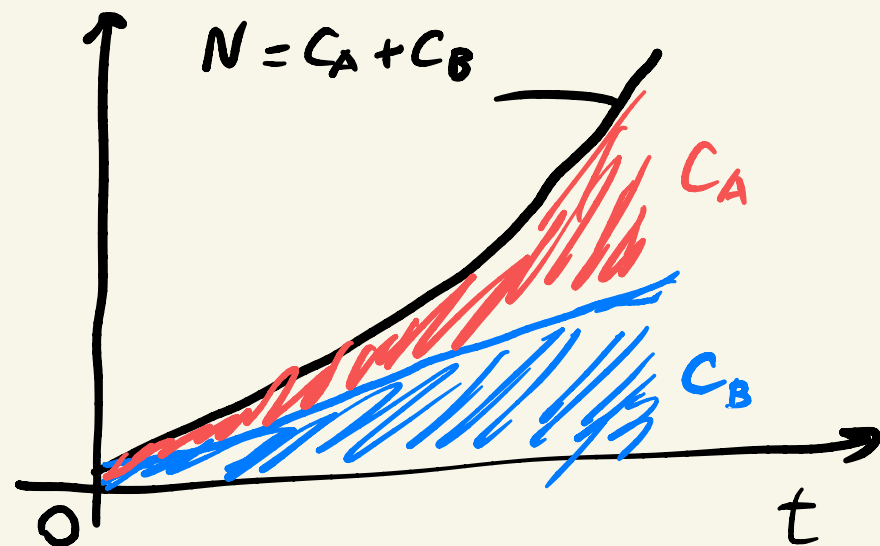
$$\begin{cases} \lambda_A P_A - \langle \lambda \rangle P_A = \alpha \\ \lambda_B P_B - \langle \lambda \rangle P_B = -\alpha \end{cases}$$

$$\rightarrow \lambda_A P_A + \lambda_B P_B - \langle \lambda \rangle (P_A + P_B) = 0$$

OK.

$$\underbrace{(\lambda_A P_A - \langle \lambda \rangle) P_A}_{\text{selection}} = \underbrace{W_{AB} P_B - W_{BA} P_A}_{\text{mutation}}$$

balanced?



Summary

- SIR model

It is difficult to obtain a steady-state
in general.

some steady states
are not achievable.

• Cell differentiation

$$\frac{d}{dt} C = S J(C)$$

$$S J(C^{st}) = 0$$

is not achievable.

$$\frac{d}{dt} P = S \tilde{J}(P)$$

$$S \tilde{J}(P^{st}) = 0$$

is achievable?

③

fitness

$$f_A = \frac{d}{dt} \ln C_A$$

$$f_B = \frac{d}{dt} \ln C_B$$

Effective growth

$$\begin{aligned} & \frac{d}{dt} (\ln(C_A + C_B)) \\ &= \frac{1}{C_A + C_B} \frac{d}{dt} C_A + \frac{1}{C_A + C_B} \frac{d}{dt} C_B \\ &= P_A f_A + P_B f_B \\ &= \langle f \rangle \end{aligned}$$

$$\frac{d}{dt} \ln P_A = - \frac{d}{dt} \ln(C_A + C_B) + \frac{d}{dt} \ln C_A$$

$$= f_A - \langle f \rangle$$

$$\frac{d}{dt} \ln P_B = f_B - \langle f \rangle$$

• Price equation

observable $R_A \in \mathbb{R}$

$R_B \in \mathbb{R}$

$$\langle R \rangle = R_A P_A + R_B P_B$$

$$\frac{d\langle R \rangle}{dt} = \left\langle \frac{dR}{dt} \right\rangle + \text{cov}(f, R)$$

$$\cdot \text{cov}(f, R) = \langle (f - \langle f \rangle)(R - \langle R \rangle) \rangle$$

☹

$$\begin{aligned} \frac{d\langle R \rangle}{dt} - \left\langle \frac{dR}{dt} \right\rangle &= \frac{d}{dt}(P_A R_A + P_B R_B) \\ &\quad - P_A \frac{dR_A}{dt} - P_B \frac{dR_B}{dt} \\ &= R_A \frac{dP_A}{dt} + R_B \frac{dP_B}{dt} \end{aligned}$$

$$P_A + P_B = 1 \quad \rightarrow \quad \frac{d}{dt}(P_A + P_B) = 0$$

$$= R_A \frac{dP_A}{dt} + R_B \frac{dP_B}{dt} - \langle R \rangle \frac{d}{dt}(P_A + P_B)$$
$$= (R_A - \langle R \rangle) \frac{dP_A}{dt} + (R_B - \langle R \rangle) \frac{dP_B}{dt}$$

$$= (R_A - \langle R \rangle) P_A \frac{d \ln P_A}{dt} + (R_B - \langle R \rangle) P_B \frac{d \ln P_B}{dt}$$

$$= (R_A - \langle R \rangle)(f_A - \langle f \rangle) P_A \\ + (R_B - \langle R \rangle)(f_B - \langle f \rangle) P_B = \text{cov}(f, R)$$

Cauchy - Schwarz inequality

$$\underset{\text{ii}}{\text{Cov}(f, f)} \underset{\text{ii}}{\text{Cov}(R, R)} \geq (\text{Cov}(R, f))^2$$

$$\text{Var}(f) \quad \text{Var}(R)$$

$$\left[\begin{array}{l} \langle a, a \rangle \langle b, b \rangle \geq \langle a, b \rangle^2 \\ \langle \dots, \dots \rangle \text{ inner product} \\ a = f - \langle f \rangle \\ b = R - \langle R \rangle \\ \langle \dots, \dots \rangle = \langle \ , \ \rangle \end{array} \right.$$

Cramér - Rao inequality

$$\text{Var}(f) \geq \frac{\text{Cov}(R, f)^2}{\text{Var}(R)} \quad \left. \begin{array}{l} \text{Price} \\ \text{eg.} \end{array} \right\}$$

$$= \frac{\left(\frac{d\langle R \rangle}{dt} - \langle \frac{dR}{dt} \rangle \right)^2}{\text{Var}(R)}$$

$$\text{Var}(f) = \left\langle \left(\frac{d \ln P}{dt} \right)^2 \right\rangle \quad : \text{ Fisher information (of } t \text{)}$$

$$= P_A \left(\frac{d \ln P_A}{dt} \right)^2 + P_B \left(\frac{d \ln P_B}{dt} \right)^2$$

$$= \frac{1}{P_A} \left(\frac{d P_A}{dt} \right)^2 + \frac{1}{P_B} \left(\frac{d P_B}{dt} \right)^2$$

$$\langle R \rangle = t, \quad \left\langle \frac{dR}{dt} \right\rangle = 0$$

$$\rightarrow \left\langle \left(\frac{d \ln P}{dt} \right)^2 \right\rangle \geq \frac{1}{\text{var}(R)}$$

Cramér - Rao

inequality.

$$\left\langle \frac{dR}{dt} \right\rangle = 0$$

$$\rightarrow \left\langle \left(\frac{d \ln P}{dt} \right)^2 \right\rangle \geq \left(\frac{\frac{d \langle R \rangle}{dt}}{\sqrt{\text{var}(R)}} \right)^2$$

$$\parallel$$

$$\text{var}(f)$$

\parallel

) speed
of R

$$\left(\frac{\frac{d \langle f \rangle}{dt} - \left\langle \frac{df}{dt} \right\rangle}{\sqrt{\text{var}(f)}} \right)^2$$

\parallel

$$\frac{ds^2}{dt^2} \leftarrow (\text{speed})^2$$

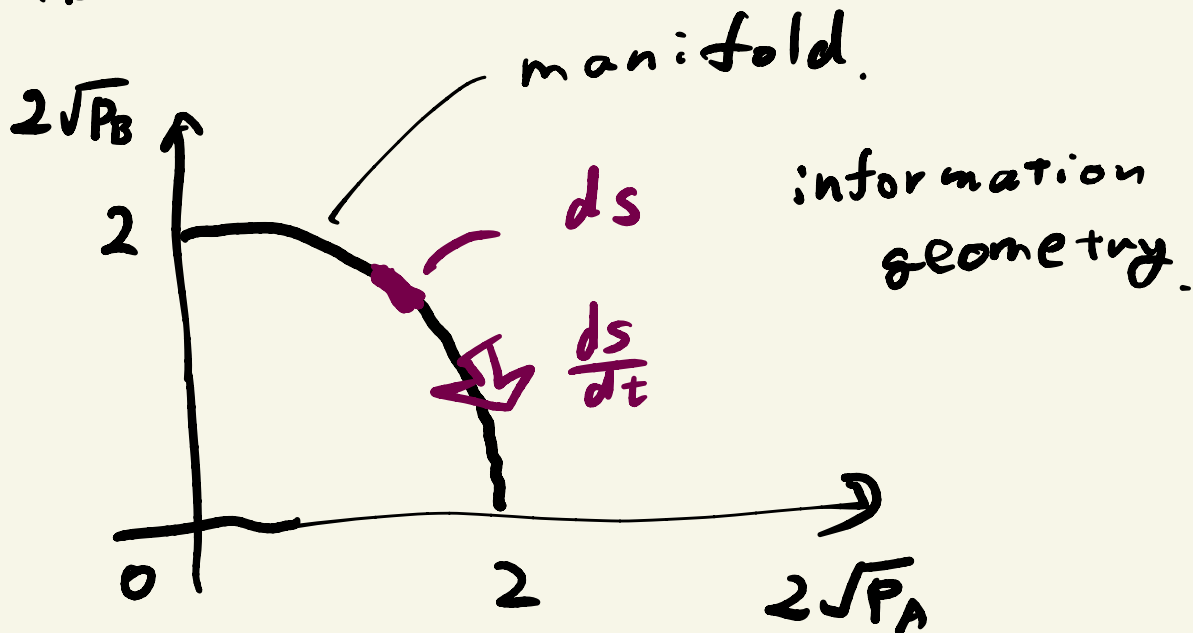
information

geometry

$$\begin{aligned}
\frac{ds^2}{dt^2} &= \left\langle \left(\frac{d}{dt} \ln P \right)^2 \right\rangle \\
&= P_A \left(\frac{d}{dt} \ln P_A \right)^2 + P_B \left(\frac{d}{dt} \ln P_B \right)^2 \\
&= \frac{1}{P_A} \left(\frac{dP_A}{dt} \right)^2 + \frac{1}{P_B} \left(\frac{dP_B}{dt} \right)^2 \\
&= \left(\frac{2 d\sqrt{P_A}}{dt} \right)^2 + \left(\frac{2 d\sqrt{P_B}}{dt} \right)^2
\end{aligned}$$

$$ds^2 = (2 d\sqrt{P_A})^2 + (2 d\sqrt{P_B})^2$$

$$P_A + P_B = 1 \rightarrow (2\sqrt{P_A})^2 + (2\sqrt{P_B})^2 = 4$$



Cramér-Rao inequality.

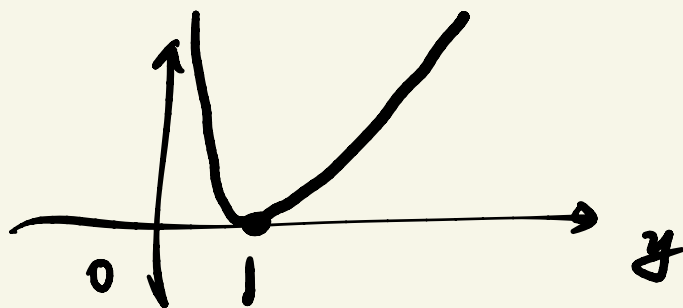
$$\frac{ds^2}{dt^2} \geq \left(\frac{\frac{d\langle R \rangle}{dt}}{\sqrt{\text{Var}(R)}} \right)^2$$

o Kullback - Leibler divergence

$$x_i > 0 \quad x_i' > 0$$

$$D_{KL}(x \parallel x') = \sum_i \left(x_i \ln \frac{x_i}{x_i'} - x_i + x_i' \right)$$
$$= \sum_i x_i f\left(\frac{x_i}{x_i'}\right)$$

$$f(y) = \ln y - 1 + \frac{1}{y}$$



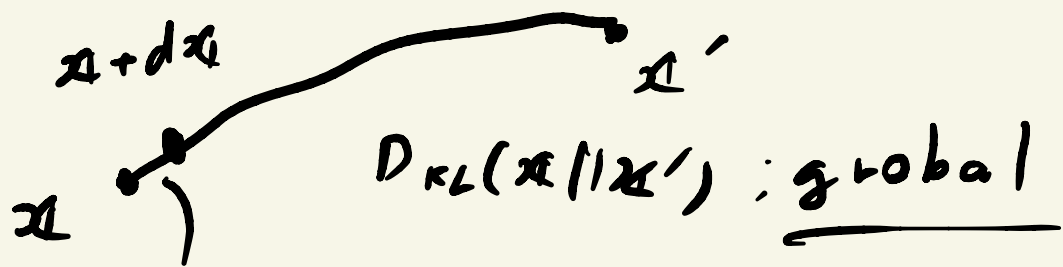
$$\textcircled{1} D_{KL}(x \parallel x') \geq 0$$

$$\textcircled{\text{☺}} f\left(\frac{x_i}{x_i'}\right) \geq 0$$
$$x_i > 0$$

$$\textcircled{2} D_{KL}(x \parallel x') = 0 \Leftrightarrow \forall_i, x_i = x_i'$$

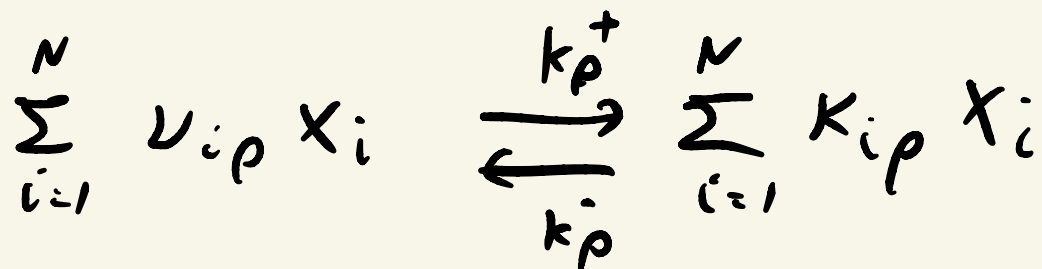
$$\textcircled{\text{☺}} f(y) = 0 \Leftrightarrow y = 1$$

$$\textcircled{3} 2 D_{KL}(x \parallel x + dx)$$
$$= \sum_i \underbrace{\frac{(dx_i)^2}{x_i}}_{ds^2} + O(dx^3)$$



$$\frac{1}{2} ds^2 = \underbrace{D_{KL}(x||x+dxi)}_{\text{local}}$$

o Chemical thermodynamics



x_i : chemical species (closed)

$$\kappa_{ip} \in \mathbb{N}, \nu_{ip} \in \mathbb{N}$$

$$p \in \{1, \dots, M\}$$

$$C = \begin{pmatrix} C_{x_1} \\ \vdots \\ C_{x_N} \end{pmatrix}$$

$$S_{ip} = \kappa_{ip} - \nu_{ip}$$

S : $N \times M$ matrix

$$J_p^+(\mathbf{c}) = k_p^+ \prod_{i=1}^N C_{x_i}^{\nu_{ip}}$$

$$J_p^-(\mathbf{c}) = k_p^- \prod_{i=1}^N C_{x_i}^{\kappa_{ip}}$$

$$J_p^+(\mathbf{c}) - J_p^-(\mathbf{c}) = J_p(\mathbf{c})$$

$$\mathbf{J}(\mathbf{c}) = \begin{pmatrix} J_1(\mathbf{c}) \\ \vdots \\ J_M(\mathbf{c}) \end{pmatrix}$$

Rate eg.

$$\frac{d}{dt} \mathbf{c} = \mathcal{S} \mathbf{J}(\mathbf{c})$$

Entropy production rate

$$\sigma = \sum_{p=1}^M J_p(\mathbf{c}) F_p(\mathbf{c}) (\geq 0)$$

$$F_p(\mathbf{c}) = \ln \frac{J_p^+(\mathbf{c})}{J_p^-(\mathbf{c})}$$

$$\begin{aligned}
\sigma &= \sum_{\rho=1}^M [J_{\rho}^{+}(\mathbf{c}) - J_{\rho}^{-}(\mathbf{c})] \ln \frac{J_{\rho}^{+}(\mathbf{c})}{J_{\rho}^{-}(\mathbf{c})} \\
&= \sum_{\rho=1}^M \left[J_{\rho}^{+}(\mathbf{c}) \ln \frac{J_{\rho}^{+}(\mathbf{c})}{J_{\rho}^{-}(\mathbf{c})} - J_{\rho}^{+}(\mathbf{c}) + J_{\rho}^{-}(\mathbf{c}) \right] \\
&\quad + \sum_{\rho=1}^M \left[J_{\rho}^{-}(\mathbf{c}) \ln \frac{J_{\rho}^{-}(\mathbf{c})}{J_{\rho}^{+}(\mathbf{c})} - J_{\rho}^{-}(\mathbf{c}) + J_{\rho}^{+}(\mathbf{c}) \right] \\
&= \underline{D_{KL}(J^{+}(\mathbf{c}) \| J^{-}(\mathbf{c})) + D_{KL}(J^{-}(\mathbf{c}) \| J^{+}(\mathbf{c}))}
\end{aligned}$$

$$J^{+}(\mathbf{c}) = \begin{pmatrix} J_1^{+}(\mathbf{c}) \\ \vdots \\ J_m^{+}(\mathbf{c}) \end{pmatrix} \quad J^{-}(\mathbf{c}) = \begin{pmatrix} J_1^{-}(\mathbf{c}) \\ \vdots \\ J_m^{-}(\mathbf{c}) \end{pmatrix}$$



geometric !

$$\sigma \geq 0$$

$$\sigma = 0 \Rightarrow J^{+}(\mathbf{c}) = J^{-}(\mathbf{c})$$

$$(J(\mathbf{c}) = \mathbf{0})$$

Assumption : detailed balanced condition

$$\cdot \frac{k_p^+}{k_p^-} = \prod_{i=1}^N (C_{x_i}^{eq})^{k_{ip} - \nu_{ip}}$$

$$F_p(\mathcal{C}) = \ln \left[\frac{k_p^+}{k_p^-} \prod_{i=1}^N (C_{x_i})^{\nu_{ip} - k_{ip}} \right]$$

$$= \ln \left[\prod_{i=1}^N \left(\frac{C_{x_i}^{eq}}{C_{x_i}} \right)^{k_{ip} - \nu_{ip}} \right]$$

$$= \sum_{i=1}^N (k_{ip} - \nu_{ip}) \ln \left(\frac{C_{x_i}^{eq}}{C_{x_i}} \right)$$

$$= \sum_{i=1}^N \mathcal{S}_{ip} \ln \left(\frac{C_{x_i}^{eq}}{C_{x_i}} \right)$$

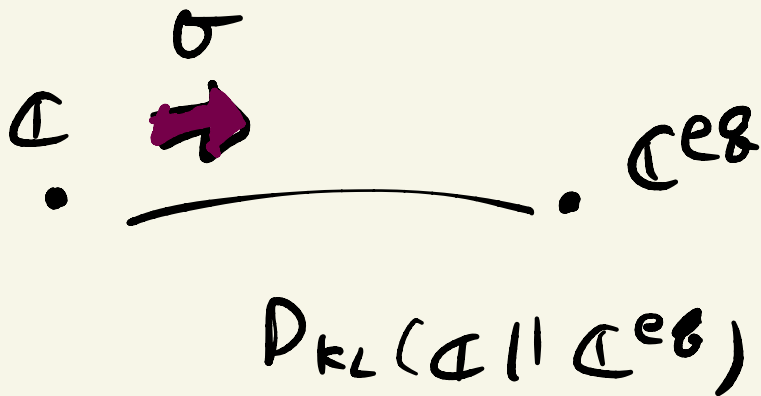
Entropy production rate

$$\sigma = \sum_{p=1}^M F_p(\mathcal{C}) J_p(\mathcal{C})$$

$$= \sum_{i=1}^N \underbrace{\left[\sum_{p=1}^M \mathcal{S}_{ip} J_p(\mathcal{C}) \right]}_{\text{Rate eq.}} \ln \left(\frac{C_{x_i}^{eq}}{C_{x_i}} \right)$$

Rate eq.

$$\begin{aligned}
\sigma &= \sum_{i=1}^N \left(\frac{dC_{x_i}}{dt} \right) \ln \frac{C_{x_i}^{eq}}{C_{x_i}} \\
&= - \frac{d}{dt} \left[\sum_{i=1}^N C_{x_i} \ln \frac{C_{x_i}}{C_{x_i}^{eq}} - C_{x_i} + C_{x_i}^{eq} \right] \\
&\quad \left(\frac{d}{dt} C_{x_i}^{eq} = 0 \right) \\
&= - \frac{d}{dt} D_{KL}(\mathcal{C} \parallel \mathcal{C}^{eq}) \quad (\geq 0)
\end{aligned}$$



speed

Summary

★ population dynamics

◦ Price eq.

$$\frac{d\langle R \rangle}{dt} = \left\langle \frac{dR}{dt} \right\rangle + \text{cov}(f, R)$$

◦ Cramér - Rao inequality

$$\text{var}(f) = \frac{ds^2}{dt^2} \geq \frac{\left(\frac{d\langle R \rangle}{dt}\right)^2}{\text{var}(R)}$$

★ chemical thermodynamics

$$\sigma = D_{KL}(\mathcal{J}^+(\mathcal{C}) \parallel \mathcal{J}^-(\mathcal{C})) \\ + D_{KL}(\mathcal{J}^-(\mathcal{C}) \parallel \mathcal{J}^+(\mathcal{C}))$$

detailed balance condition

$$\Rightarrow \sigma = -\frac{d}{dt} D_{KL}(\mathcal{C} \parallel \mathcal{C}^{eq})$$